

01 Introduction



Congratulations and thank you for your trust in Hobbywing product. By purchasing the XERUN XD10 Pro, you have chosen a high performance sensorless brushless electronic speed controller! This speed controller is equipped with high-tech features to enhance your experience with Hobbywing brushless power systems. Improper usage and unauthorized modification to our product is extremely dangerous and may damage the product and related devices. Please take your time and read the following instructions carefully before you start using your speed control. We have the right to modify our product design, appearance, features and usage requirements without notification. We, HOBBYWING, are only responsible for our product cost and nothing else as result of using our product.

XERUN USER MANUAL Brushless Electronic Speed Controller XERUN XD10 Pro

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02 Warnings

- To avoid short circuits, ensure that all wires and connections must be well insulated before connecting the ESC to related devices.
- Ensure all devices are well connected to prevent poor connections and avoid damage to your electronic devices.
- Read through the manuals of all power devices and chassis and ensure the power configuration is rational before using this unit.
- Please use a soldering iron with the power of at least 60W to solder all input/output wires and connectors.
- Do not hold the vehicle in the air and rev it up to full throttle, as rubber tires can "expand" to extreme size or even crack to cause serious injury.
- Stop immediate usage once the casing of the ESC exceeds 90°C/194°F as this may cause damage to both the ESC and motor. Hobbywing recommends setting the "ESC Thermal Protection" to 105°C/221°F (this refers to the internal temperature of the ESC).
- Users must always disconnect the batteries after use as the current on the ESC is consuming continuously if it is connected to the batteries (even if the ESC is turned off). The battery will completely be discharged and may result in damage to the battery or ESC when it is connected for a long period of time. This WILL NOT be covered under warranty.

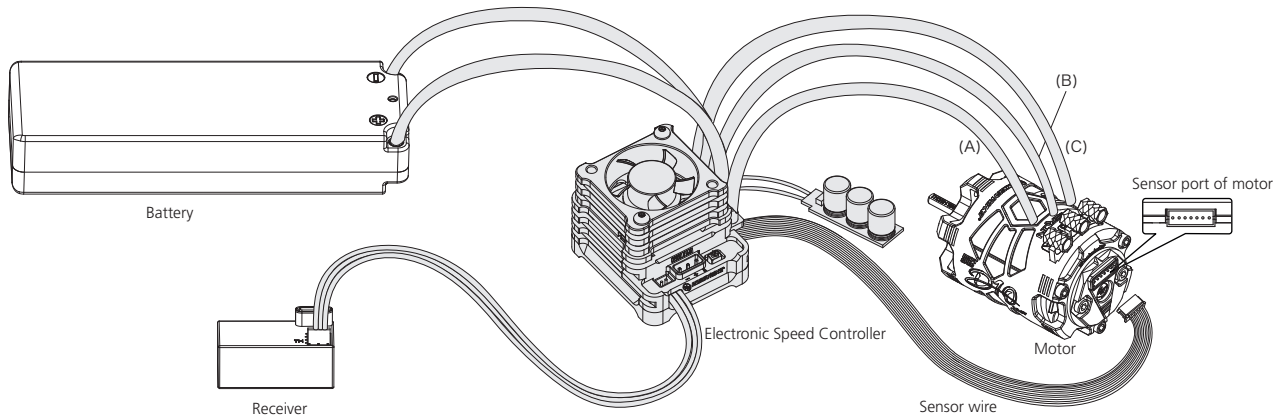
03 Features

- Built-in switch mode BEC with a maximum output of 10A and voltage adjustable from 5V to 7.4V (step: 0.1V) for usage with servos & other devices require different voltages.
- Separate PRG/FAN port is able to power an external fan for maximize cooling performance or connect a LCD program box or WiFi module to the ESC.
- Variable frequency regulation of PWM & brake frequencies allows users to precisely regulate the driving & braking forces (of the motors).
- Multiple protections: low-voltage cutoff protection, ESC and motor thermal protection, and fail safe (throttle signal loss protection), reverse polarity protection (the external standard cappaack will still be damaged if battery reversal occurs).
- Data logging for recording the maximum ESC/motor temperature, motor RPM, and others in real time.
- Firmware upgrade via Hobbywing multifunction LCD program box or OTA Programmer (item sold separately).

04 Specifications

Model	XERUN XD10 Pro
Cont./Peak Current	100A / 800A
Motor Type	Sensored / Sensorless Brushless Motors
Applications	1/10 th drift car
Motor Limit*	Brushless Motor Limit with 2S LiPo/6S NiMH: >=8.5T
LiPo/NiMH Cells	2S LiPo / 4-6S NiMH
BEC Output	5-7.4V Adjustable, Continuous Current of 5A (Switch-mode)
Cooling Fan	Powered by the stable BEC voltage of 5-7.4V
Size	40 7x35.0x32.0mm (w/Fan)
Weight	95g (w / wires)
Programming Port	PRG Port

05 Connections



This is an extremely powerful brushless motor system. For your safety and the safety of those around you, we strongly recommend removing the pinion gear attached to the motor before performing calibration and programming functions with this system. It is also advisable to keep the wheels in the air when you turn on the ESC.

- Motor Wiring:** The motor wiring is different between the sensed and the sensorless; please only follow the introductions below.
 - Sensored Motor Wiring**
There is strict wiring order from the ESC to the motor, the three A/B/C ESC wires must connect to the three A/B/C motor wires correspondingly. Next, connect the ESC sensor port and the motor sensor port with the stock 6-pin sensor cable. If you don't plug the sensor cable in, your ESC will still work in sensorless mode even if you're using a sensed motor.
 - Sensorless Motor Wiring**
Users do not need to be worried in regards to the connectivity with the A/B/C(ESC and motor) as there is no polarity. You may find it necessary to swap two wires if the motor runs in reverse.
- Receiver Wiring:** The throttle control cable on the ESC has to be plugged into the throttle (TH) channel on the receiver. The throttle control cable has an output voltage of 6V/7.4V to the receiver and steering servo, hence, no separate battery can be connected to the receiver. Otherwise, your ESC may be damaged.
- Battery Wiring:** Proper polarity is essential. Please ensure positive (+) connects to positive (+), and negative (-) connects to negative (-) when plugging in the battery! When reverse polarity is applied to the ESC from the battery, the external standard cappaack will still be damaged.

06 ESC Setup

1 ESC/Radio Calibration

Begin using your ESC by calibrating with your transmitter. We strongly recommend Hobbywing users to use the "Fail Safe" function on the radio system and set (F/S) to "Output Off" or "Neutral Position". Example of calibrating Neutral range and Endpoint.

Release the ON/OFF button once the LED flashes.

Press the ON/OFF button. The Green LED flashes once and motor emits "Beep" tone.

Press the ON/OFF button. The Green LED flashes twice and motor emits "Beep" tone.

Press the ON/OFF button. The Green LED flashes three times and motor emits "Beep" tone.

- Turn on the transmitter, ensure all parameters (D/R, Curve, ATL) on the throttle channel are at default (100%). For transmitter without LCD, please turn the knob to the maximum, and the throttle "TRIM" to 0. Please also turn the corresponding knob to the neutral position.
- Start by turning on the transmitter with the ESC turned off but connected to a battery. Holding the "ON/OFF" button, the RED LED on the ESC starts to flash (Note 2: the motor beeps at the same time), and then release the ON/OFF button immediately.
Note: Beeps from the motor may be low sometimes, and you can check the LED status instead.
- Set the neutral point, the full throttle endpoint and the full brake endpoint.
 - Leave transmitter at the neutral position, press the "ON/OFF" button, the RED LED dies out and the GREEN LED flashes 1 time and the motor beeps 1 time to accept the neutral position.
 - Pull the throttle trigger to the full throttle position, press the "ON/OFF" button, the GREEN LED blinks 2 times and the motor beeps 2 times to accept the full throttle endpoint.
 - Push the throttle trigger to the full brake position, press the "ON/OFF" button, the GREEN LED blinks 3 times and the motor beeps 3 times to accept the full brake endpoint.
- The end position of forward: Pull the trigger to the maximum throttle position if it is pistol-style transmitter. Push the throttle to the top if it is board-style transmitter.
- The end position of backward: Push the trigger to the maximum brake position if it is pistol-style transmitter. Pull the throttle to the bottom if it is board-style transmitter.
- The motor can be started 3 seconds after the ESC/Radio calibration is complete.

2 Power On/Off

Attention! The temperature of its Aluminum housing may be very high when there is heavy load. For precaution, we recommend users to have a fan blown towards the ESC. (Start with the ESC turned off, press the ON/OFF button to turn on the ESC (the indication LED comes on), and press the ON/OFF button again to turn off the ESC (the indication LED dies out). **Note:** Do not turn off the ESC when the motor is spinning. The sudden stoppage may result in unwanted damage to both the motor and ESC. If there is an emergency, battery plugs can be pulled out to switch the ESC off.

3 Programmable Items

Section	Item	Programmable Items			Parameter Values															
General Setting	1A	Running Mode			Forward with Brake			Forward/ Reverse with Brake			Forward and Reverse									
	1B	Max. Reverse Force			25%			50%			75%		100%							
	1C	Reverse Delay			0-55 (Adjust Step 0.5S)															
	1D	Cutoff Voltage			Disabled			Auto (3.3V/Cell)			3.0-7.4V Adjustable (Step: 0.1V)									
	1E	ESC Thermal Protection			Disabled			105°C/221°F			125°C/257°F									
	1F	Motor Thermal Protection			Disabled			105°C/221°F			125°C/257°F									
	1G	BEC Voltage			5V-7.4V Adjustable (Step:0.1V)															
	1H	Remote Off			Disabled			Enabled												
	1I	Motor Rotation			CCW			CW												
	1J	Phase-AC Swap			Disabled			Enabled												
Throttle Control	2A	Throttle Rate Control			1-30 Adjustable (Step: 1)															
	2B	Throttle Curve			Linear			Customized												
	2C	Neutral Range			3%-10% (Adjust Step1%)															
	2D	Initial Throttle Force			1-15 (Adjust Step 1)															
	2E	Coast			0%-15% (Adjust Step 1%)															
	2F	PWM Drive Frequency			1K	2K	4K	8K	12K	16K	24K	32K	40K	48K	Customized					
Brake Control	3A	Softening Value			0-30° Adjustable (Step: 1°)															
	3B	Softening Range			0%	10%	20%	25%	30%	35%	40%	45%	50%	55%	60%	65%	70%	75%		
	3C	Initial Brake Force			=Drag brake			0%-100% Adjustable (Step: 1%)												
	3D	Brake Rate Control			1-20 Adjustable (Step: 1)															
	3E	Brake Curve			Linear			Customized												
	3F	Brake Frequency			0.5K	1K	2K	4K	8K	12K	16K	20K	24K	Customized						
Timing	4A	Boost Timing			0-64° Adjustable (Step: 1°)															
	4B	Boost Timing Activation			RPM			Auto												
	4C	Boost Start RPM			500-35000RPM (Step: 500RPM)															
	4D	Boost End RPM			3000-60000RPM (Step: 500RPM)															
	5A	Turbo Timing			0-64° Adjustable (Step: 1°)															
	5B	Turbo Delay			Instant	0.05s	0.1s	0.15s	0.2s	0.25s	0.3s	0.35s	0.4s	0.45s	0.5s	0.6s	0.7s	0.8s	0.9s	1.0s
	5C	Turbo Increase Rate (deg/0.1sec)			3deg/0.1s	6deg/0.1s	9deg/0.1s	12deg/0.1s	15deg/0.1s	18deg/0.1s	21deg/0.1s	24deg/0.1s	27deg/0.1s	30deg/0.1s	Instant					
	5D	Turbo Decrease Rate (deg/0.1sec)			3deg/0.1s	6deg/0.1s	9deg/0.1s	12deg/0.1s	15deg/0.1s	18deg/0.1s	21deg/0.1s	24deg/0.1s	27deg/0.1s	30deg/0.1s	Instant					

Note: Item 4C (Boost Start RPM) & Item 4D (Boost End RPM) are not programmable if item 4B (Timing Activation) is set to "Auto".

1A. Running Mode

Option 1: Forward with Brake
Racing mode. It has only forward and brake functions.

Option 2: Forward/ Reverse with Brake

This option is known to be the "training" mode with "Forward/ Reverse with Brake" functions. Hobbywing has adopted the "DOUBLE-CLICK" method, that is your vehicle only brakes on the 1st time you push the throttle trigger forward (brake) (1st push). The motor stops when you release the throttle trigger and then re-push the trigger (2nd push), only then the vehicle will reverse. The reverse function will not work if your car does not come to a complete stop. The vehicle only reverses after the motor stops. This method is for preventing vehicle from being accidentally reversed.

Option 3: Forward and Reverse

This mode is often used by special vehicles (rock crawler). It adopts the "SINGLE-CLICK" method. The vehicle will reverse immediately when you push the throttle trigger forward (brake).

1B. Max. Reverse Force

The reverse force of the value will determine its speed. For the safety of your vehicle, we recommend using a low amount.

1C. Reverse Delay

This parameter is used to adjust and set the delay time when the reverse output is being applied; When the motor is at a standstill, the reverse output will be activated once the delay time of the value is reached.

1D. Cutoff Voltage

Sets the voltage at which the ESC lowers or removes power to the motor in order to either keep the battery at a safe minimum voltage (for LiPo batteries). The ESC monitors the battery voltage all the time, it will immediately reduce the power to 50% (in 3 seconds) and cut the output 40 seconds later when the voltage goes below the cutoff threshold. The RED LED will flash a short, single flash that repeats (☆, ☆, ☆) to indicate the low-voltage cutoff protection is activated. Please set the "Cutoff Voltage" to "Disabled" or customize this item if you are using NiMH batteries.

Option 1: Disabled

The ESC does not cut the power off due to low voltage. We do not recommend using this option when you use any LiPo battery as you will irreversibly damage the product. You need to select this option when you are using a NiMH pack.

Option 2: Auto

The ESC calculates the corresponding cutoff voltage for the battery shall be 6.6V.

Option 3: Customized

The customized cutoff threshold is a voltage for the whole battery pack (adjustable from 3.0V to 7.4V).

1E. ESC Thermal Protection

The output from the ESC will be cut off with the value you have preset. The GREEN LED flashes (☆☆, ☆☆, ☆☆) when the ESC temperature reaches to the preset value. The output will not resume until the ESC temperature gets down.

Warning! Please do not disable this function unless you're in a competition. Otherwise the high temperature may damage your ESC and even your motor.

1F. Motor Thermal Protection

The GREEN LED flashes (☆☆☆, ☆☆☆, ☆☆☆) when the motor temperature reaches to the preset value. The output will not resume until the motor temperature gets down.

Warning! Please do not disable this function unless you're in a competition. Otherwise the high temperature may damage your motor and even your ESC. For non-Hobbywing motor, the ESC may get this protection activated too early/late because of the different temperature sensor inside the motor. In this case, please disable this function and monitor the motor temperature manually.

1G. BEC Voltage

BEC voltage can be adjusted between 5.0-7.4V. 6.0V is applicable to common servo. If use high-voltage servo, set to higher voltage according to voltage marking of servo.

1H. Remote Off

Option 1: Enabled

Users can simply push and hold the brake trigger for 6 seconds. This option allows the user to turn off the ESC without pushing the ON/OFF button switch.

Option 2: Disabled

Users must turn off the ESC by pressing the ON/OFF switch button from the ESC.

1I. Motor Rotation/Direction

With the motor shaft faces you (the rear end of the motor is away from you), increase the throttle input, the motor (shaft) will rotate in the CCW/CW direction if the "Motor Rotation/Direction" is set to "CCW/CW". Generally, the vehicle runs forward when the motor (shaft) rotates in the CCW direction. However, some vehicles only run forward when the motor rotates in the CW direction due to the different chassis design. In that case, you only need to set the "Motor Rotation/Direction" to "CW".

1J. Phase-AC Swap

If the A/C wire of ESC connect to A/C wire of motor with crossed way (A wire of ESC connects to C wire of motor, C wire of ESC connects to A wire), set this item as Enable.

2A. Throttle Rate Control

This item is used to control the throttle response. It can be adjustable from 1 to 30 (step: 1), the lower the throttle rate, the more the limit will be on the throttle response. A suitable rate can help driver to control his vehicle properly during the starting-up process. Generally, you can set it to a high value to have a quick throttle response if you are proficient at throttle control.

2B. Throttle Curve

The throttle curve parameter reconciles the position of the throttle trigger (in throttle zone) and the actual ESC throttle output. It is linear by default and we can change it to non-linear via adjusting the throttle curve. For example, if adjust it to +EXP, the throttle output at the early stage will be higher (than the input when the curve is linear); if it is adjusted to -EXP, the throttle output at the early stage will be lower (than the output when the curve is linear).

2C. Neutral Range

As not all transmitters have the same stability at "neutral position", please adjust this parameter as per your preference. You can adjust to a bigger value when this happens.

2D. Initial Throttle Force

It also called as minimum throttle force. You can set it according to wheel tire and traction. If the ground is slippery, please set a small throttle force. Some motors have strong cogging effect with lower FDR number. When you push throttle a little bit, the motor will not rotate until a higher throttle point than the default initial throttle point. When we have this parameter, we can use the transmitter turn to check the above issue and then adjust the best initial throttle point by increasing the ITF a little. The control feeling will be smoother if you find the best point. Normally the number will be not over 5%.

2E. Coast

The RPM of the motor will be lowered gradually when the throttle is reduced. The vehicle will not reduce speed abruptly when the throttle is reduced to return to the neutral position. The bigger the value, the more the "COAST" will be felt. Example, COAST of 0 deactivates, and a COAST of 15% would be the maximum amount of COAST.

What is COAST?

When a vehicle has a larger final drive ratio, the tendency of having a "drag" feel is higher. The "COAST" technology is to allow the car to roll (coast) even when the final drive ratio is high. The Coast function brings better and smoother control feeling to racers. Some drivers will refer to this to the traditional brushed motors.

Note: The "Coast" will be void (even if you set it to any value besides 0) if the above "drag brake" is not "0%".

PWM Drive Frequency

The acceleration will be more aggressive at the initial stage when the drive frequency is low; a higher drive frequency is smoother but this will create more heat to the ESC. If set this item to "Customized", then the PWM frequency can be adjusted to a variable value at any 0-100% throttle input, Please choose the frequencies as per the actual test results of your vehicles.

2G. Softening Value

It allows users to fine-tune the bottom end, change the driving feel, and maximize the driving efficiency at different track conditions. The higher the "Softening Value", the milder the bottom end. In Modified class, drivers often feel the power of the bottom end is too aggressive. Little throttle input usually brings too much power to the car and make it hard to control at the corners, so HOBBYWING creates this softening function to solve the issue.

Note: You can increase the motor mechanical timing accordingly after you set the softening value. Every time you increase the softening value by 5 degrees, you can increase the mechanical timing by 1 degree. For example, if you set the softening value to 20 degrees, then you can increase the mechanical timing by 4 degrees. Please note that you will never increase the mechanical timing by over 5 degrees.

2H. Softening Range

It's the range to which "Softening Value" starts and ends. For example, 0% to 30% will be generated when the user pre-programs the "Softening Range" at a value of 30%.

3A. Drag Brake

It is the braking power produced when releasing from full speed to neutral position. This is to simulate the slight braking effect of a neutral brushed motor while coasting. It's not recommended for buggy and monster truck.

(Attention!) Drag brake will consume more power and heat will be increased, apply it cautiously.)

3B. Max. Brake Force

This ESC provides proportional braking function; the braking effect is decided by the position of the throttle trigger. It sets the percentage of available braking power when full brake is applied. Large amount will shorten the braking time but it may damage your pinion and spur.

3C. Initial Brake Force

It is also known as "minimum brake force". It is the force when pushing throttle trigger from neutral zone to the initial brake position. To get a smoother braking effect, the default is equal to the drag brake.

3D. Brake Rate Control

It's adjustable from 1 to 20 (step: 1), the lower the brake rate, the more limit on the brake response. A suitable rate can aid the driver to brake his vehicle correctly. Generally, you can set it to a high value to have a quick brake response.

3E. Brake Curve

This item is used for regulating the relationship between the throttle range in brake zone and the brake force. The default setting is linear. You can change it to non-linear via a LCD program box and a PC (HOBBYWING USB LINK software needs to be installed on the PC.) for different braking effect.

3F. Brake Frequency

The brake force will be larger if the frequency is low; you will get a smoother brake force when the value is higher. If set this item to "Customized", then the brake frequency can be adjusted to a variable value at any 0-100% throttle input, Please choose the frequencies as per the actual test results of your vehicles.

4A. Boost Timing

It is effective within the whole throttle range; it directly affects the car speed on straightaway and winding course. The ESC adjusts the timing dynamically as per the RPM (when "Boost Timing Activation" set to "RPM") or throttle amount (when "Boost Timing Activation" set to "Auto") in the operation. The Boost Timing is not constant but variable.

4B. Boost Timing Activation

Option 1: RPM

In RPM mode, the ESC adjusts the Boost Timing dynamically as per the motor speed (RPM). The actual Boost Timing is 0 when the RPM is lower than the Boost Start RPM. The Boost Timing changes as per the RPM when the RPM change is between the Boost Start RPM and the Boost End RPM. For example, if the Boost Timing is set to 5 degrees and the Boost Start RPM is 10000, the Boost End RPM is 15000. The Boost Timing corresponds to different RPM is shown below. When the RPM is higher than the Boost End RPM, the actual Boost Timing is the value you had previously set.

RPM (Motor Speed)	<10000	10001-11000	11001-12000	12001-13000	13001-14000	14001-15000	>15000
Actual Boost Timing	0 Degree	1 Degree	2 Degrees	3 Degrees	4 Degrees	5 Degrees	5 Degrees

Option 2: Auto

In Auto mode, the ESC adjusts the Boost Timing dynamically as per the throttle amount. Only at full throttle, the actual Boost Timing is the value you had previously set.

4C. Boost Start RPM

This item defines the RPM at which Boost Timing is activated. For example, when the Boost Start RPM is set to 5000, the ESC will activate the corresponding Boost Timing when the RPM goes above 5000. The specific value is determined by the Boost Timing and the Boost End RPM you had previously set.

4D. Boost End RPM

This item defines the RPM at which Boost Timing (you specifically set) is applied. For example, when Boost Timing is set to 10 degrees and the Boost End RPM to 15000, the ESC will activate the Boost Timing of 10 degrees when the RPM goes above 15000. The ESC will adjust the Boost Timing accordingly as per the actual RPM when the RPM goes below 15000.

5A. Turbo Timing

This item is adjustable from 0 degree to 64 degrees, the corresponding turbo timing (you set) will initiate at full throttle. It's usually activated on long straightaway and makes the motor unleash its maximum potential.

5B. Turbo Delay

When "TURBO DELAY" is set to "INSTANT", the Turbo Timing will be activated right after the throttle trigger is moved to the full throttle position. When other value(s) is applied, you will need to hold the throttle trigger at the full throttle position (as