# 01 Disclaimer

Thank you for purchasing this HOBBYWING product! Any improper use may cause personal injury and damage to the product and related devices. We strongly recommend reading through this user manual before use and strictly abide by the specified operating procedures. We shall not be liable for any liability arising from the use of this product, including but not limited to reimbursement for incidental or indirect losses. Meanwhile, we do not assume any responsibility caused by unauthorized modification of the product. We have the right to change the product design, appearance, performance and use requirements without notice.

# **02** Attentions

• Please make sure that all wires and connecting parts are well insulated before the ESC connected with relevant connecting parts, because short circuit will damage the ESC • Please connect all parts carefully. If connect improperly, you may not be able to control the vehicle normally, or the equipment will be damaged or other unpredictable situations occurs.

- Before using this system, please carefully check each power device and car frame instructions to ensure the power matching is reasonable. Prevent wrong matching from damaging power system. • If need to weld input line, output line and plug of ESC, please use welding equipment of at least 60W to ensure weld firmly.
- Do not let the external temperature of the system exceed 90°C/194°F, high temperature will destroy the power system.

RUICRUN

**USER MANUAL** 

QuicRun Fusion BL SYS for

Crawler-540Spec

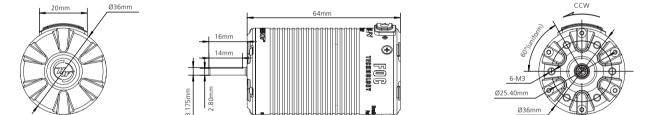
• After use, remember to disconnect the battery and the ESC. If the battery isn't disconnected, the ESC will consume electric energy all the time even if it is off. It will discharge completely if connect the battery for a long time, thus resulting in the failure of the battery or the ESC. We are not responsible for any damage caused by this!

# **03** Features

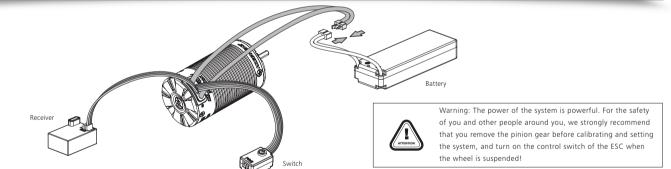
- The integrated design of the ESC and the motor greatly reduces the overall volume and weight, and makes the layout and wiring of car frame simpler and more convenien
- The FOC driving mode, low speed torque is strong. Smooth running at extreme low speed, which is far superior to the common sensored brushless power system, even better than the brushed power • Thanks to the sine wave driving mode, the whole system has high efficiency, small heat, and effectively extends the endurance time; and the motor runs more quietly and soft.
- The protection grade of the whole set of power is IP67, with excellent waterproof and dustproof performance. Under various weather conditions, the whole set of power can easily deal with the complex road surface containing silt, ice and snow, and water.
- Intelligent torque output and speed closed-loop control, fully experience the cruise control and steep slope slow descent function of 1:1 vehicle, making the control handy. · Active drag brake force adjustment, providing unprecedented parking capacity on slope.
- With strong built-in switch mode BEC, the continuous current is up to 4A, and support switch between 6V and 7.4v, easy to drive various powerful steering servo and high-voltage steering servo. • Equipped with advanced and safe electronic switch to avoid reed stuck and contact rusted of traditional mechanic switch in dusty and damp environment, and automatic close of mechanic switch due to fierce impact
- Multiple protection functions: battery low voltage protection, overheat protection, throttle lost protection, lock-up protection
- It supports LED setting box to set ESC parameters, and has independent parameter setting interface, which is integrated on electronic switch, making setting parameters more convenient

## **04** Specifications

| Continuous peak current               | 40A/160A   |
|---------------------------------------|--|
| Main applications                     | 1/10 rock crawler  |
| LiPo/NiMH Cells                       | 2-3S Lipo, 6-9 Cells NiMH                                |
| BEC output                            | 6V/7.4V adjustable, continuous current 4A (Switch mode)  |
| Input plug                            | XT60   |
| Size/Weight(entirety)                 | 36mm(diameter)x64mm(length) / 201g (including wire plug) |
| Parameter setting                     | Independent programming interface(switch position)       |
| Motor KV                              | 1200KV , 1800KV  |
| Diameter/length of Motor              | 36mm / 64mm  |
| Shaft diameter / exposed shaft length | 3.175mm / 16mm   |
| Motor Poles                           | 4 poles  |



## **05** Begin to Use a New Brushed ESC



#### Connect receive

Insert the throttle control flat cable of the ESC into the throttle channel of receiver (that's THROTTLE channel). Because the red line of flat cable output 6V/7.4V voltage to receiver and steering servo, do not supply power to receiver, otherwise the ESC may be damaged. If need to supply power, pick out the red line among throttle line, wrap it and suspence

## Connect battery

The input line of the ESC has polarity. When inserting the battery, make sure that the (+) pole of the ESC is connected to the (+) pole of the battery and the (-) pole is connected to the (-). If the ESC is connected reversely, the ESC will be damaged. There is no warranty service for damaging ESC due to power on reversely.

## Instruction for power on/off and Tones

Instruction for power on/off: Short press the switch button to start in off state; long press the switch button to shut down in on state.

Instruction for sound: Start in normal condition (Not setting throttle range), the times of beep emitted by motor indicates the number of Lipo Cells, for example, "Beep," indicates 2S Lipo; "Beep Beep, Beep" indicates 3S Lipo.

## Instruction for programmable items

The column of white words on black background in the following table are the default values of programmable items.

| No. | Setting item           | Option 1    | Option 2    | Option 3     | Option 4 | Option 5 | Option 6 | Option 7 | Option 8 | Option 9 |
|-----|------------------------|-------------|-------------|--------------|----------|----------|----------|----------|----------|----------|
| 1   | RPM/Throttle Matching  | Enabled     | Disabled    |              |          |          |          |          |          |          |
| 2   | LiPo/NiMH Cells        | Auto        | 25          | 35           |          |          |          |          |          |          |
| 3   | Cutoff Voltage         | Disabled    | Low         | Intermediate | High     |          |          |          |          |          |
| 4   | ESC Thermal Protection | 105°C/221°F | 125°C/257°F | Disabled     |          |          |          |          |          |          |
| 5   | Motor Rotation         | CCW         | CW          |              |          |          |          |          |          |          |
| 6   | BEC Voltage            | 6.0V        | 7.4V        |              |          |          |          |          |          |          |
| 7   | Drag Brake Force       | Disabled    | Level 1     | Level 2      | Level 3  | Level 4  | Level 5  | Level 6  | Level 7  | Level 8  |
| 8   | Drag Brake Rate        | Level 1     | Level 2     | Level 3      | Level 4  | Level 5  | Level 6  | Level 7  | Level 8  | Level 9  |
| 9   | Max. Reverse Force     | 25%         | 50%         | 75%          | 100%     |          |          |          |          |          |

### 1. RPM/Throttle Matching

Option 1: Enabled Through speed closed-loop control to realize cruised control function, that is, when the resistance of the vehicle changes, the ESC will automatically adjust the output torque

### **Option 2: Disabled**

Like common sensored brushless ESC, the ESC will not automatically adjust the output torque in this mode, that is, when the resistance of the vehicle changes, the speed will change accordingly. 2. Lipo Cells:

The default is automatic judgement. If you usually use the same battery, we suggest you set manually the number of Lipo Cells to avoid misjudgment (Which may mistakenly judge 35 Lipo that have no power as 2S Lipo that are fully charged, which will cause the low-voltage protection function of the ESC operates wrongly.

#### 3. Cutoff Voltage

This function is mainly to prevent the irrecoverable damage caused by over discharge of Lipo Cells. If the voltage protection is turned on, the ESC will monitor the battery voltage all the time during operation. Once the voltage is lower than the set threshold value, the power output will gradually reduce to 50% of the normal power within 3 seconds, and the power will be completely closed after 10 seconds. When entering the low-voltage protection, the red LED will blink in the way of "\$\arrow -, \$\arrow -, When using Lipo Cells, it is not recommended to set to (no protection), otherwise the battery may be damaged due to over discharge. For NIMH batteries, it is recommended to set this parameter to no protection. The low, medium and high options correspond to 3.0v/3.2v/3.4v respectively.

#### 4. ESC Thermal Protection:

The ESC will close output automatically when the temperature rises to the preset value, and the green light will flash, and the output will be restored until the temperature drops. The green light flashes in the way of  $rac{a}{-}$ ,  $rac{a}{-}$ ,  $rac{a}{-}$  in single cycle  $\circ$   $\circ$   $\circ$   $\circ$  when in overheat protection.

#### 5. Motor Rotation:

The front of the motor shaft faces the user's face (i.e. the tail of the motor is far away from the user's face, when the radio is increasing the throttle in the forward direction, if it is set to CCW, the motor shaft rotates counterclockwise; if it is set to CW, the motor shaft rotates clockwise. Due to the structure difference of car frame, the rotation direction would not correct. If the rotation direction is wrong, change to the reverse direction

## 6. BEC Voltage

Option 1: 6.0V

Apply to ordinary servo, if use high voltage servo, do not set to this, otherwise it will not work normally due to insufficient voltage.

Option 2: 7.4V

Apply to high voltage servo, if use ordinary servo, do not set to this, otherwise it will damage steering servo due to high voltage

## 7. Drag Brake Force:

Drag brake means a brake force on the motor when the throttle trigger moves from the non-neutral range to the neutral range. There are 9 gears of drag brake force to adjust, "off" means the drag brake force is 0; the corresponding drag brake force increases from 1 gear to 8 gear. Select the appropriate drag brake force according to the actual situation

#### 8. Drag Brake Rate: It means the rate when drag brake force increases from zero to the set value when the radio trigger enters the neutral range, commonly called as slow brake. This value has 9 gears to adjust. The higher the gear is, the greater the drag brake rate is. Reasonably set this value can make the vehicle stop more stably.

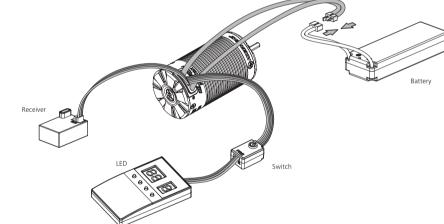
9. Max. Reverse Force:

Select different parameter value can produce different max. reverse force

## **4** Parameter setting method

#### Use LED setting box to set ESC parameters

The ESC is equipped with a LED box. The LED box is small and suitable for outdoor use. The interface is intuitive. It is easy and fast to read and set parameters. The setting method is as follows: The ESC is in off state, connect the 3pin setting interface on the 2 in 1 system switch with the interface marked with - + V on the upper right corner of the setting box according to the polarity with a flat cable with JR plug at both ends. Then power on the ESC, after a few seconds, all parameters of the ESC can be displayed. The "ITEM" and "VALUE" button on the programming card can quickly select the programming items and parameter values, press "OK" key to save the new parameters in ESC.



## Factory reset

Use LED setting box to restore factory settings. The method is as follows:

After connect setting card and the ESC, press "RESET" key and then press "OK" key to save, the factory settings can be restored.

## Automatic Motor Pairing(Optional)

If the motor has been subjected to severe impact or has abnormal heating and abnormal power output during operation, need to do the following automatic motor pairing. The operation method is as follows:

Step 1: Pull out the throttle line from the receiver and remove the motor gear

Step 2: Connect the battery, long press and start key, the switch of ESC will flash the red light first, then switch to green light flashing after about 8 seconds, now enter the automatic motor pairing process. The motor will automatically rotate if release the button, wait for the motor to end the rotation and the red light starts flashing, indicating that the automatic motor pairing is completed. Step 3: After the automatic motor pairing is completed, the ESC will self-check (report Lipo Cells). Reconnect the throttle line to operate normally.

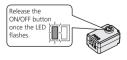
Note: Please remove the motor gear before operation, otherwise it may lead to incorrect matching and unknown risk

# 07 Indication for LED of ESC

# **06** ESC Setup

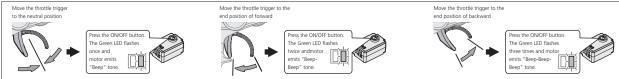
## Set the Throttle Range – ESC Calibration – Radio Setup

Before the first use of ESC or after the radio changed parameters of throttle channel "TRIM" > D/R EPA, the throttle range needs to be reset. Otherwise the ESC may be unable to use or wrong action. We strongly recommend to turn on fail safe function, set the no signal protection function of throttle channel ("F/S") to close output mode or set the protection value to the midpoint position, making the motor stop running when the receiver cannot receive signal of the radio. Adjust the throttle as following:



1. Turn on the radio, adjust the "D / R", "EPA", "ATL" of the throttle channel to 100% (if the radio has no display screen, adjust the corresponding knob to the maximum position), and adjust the "TRIM" of the throttle channel to 0 (if the remote control has no display screen, adjust the corresponding knob to the middle position). Futaba and similar radio need to set the throttle channel direction to "REV", and the throttle channel direction of other brands radio should be set to "NOR". Be sure to turn off the ABS brake function of the radio.

2. In power off state, press the power key and hold it continuously. The red light on the ESC's switch starts to flash (and the motor sounds at the same time), then release the key immediately (If the key is not released within 8 seconds, the ESC will enter other modes)



- 3. At this time, three points need to be set: the neutral position, the end position of forward and the end position of backward.
- The throttle trigger stays at the neutral position, press the SET key, the red light goes out, the green light flashes once, and the motor emits "beep" once, indicating that the neutral position has been stored
- Move the throttle trigger to the end position of forward, press SET key, the green light flashes twice, and the motor emits "beep" twice, indicating that the end position of forward has
- Push the throttle trigger to the end position of backward, press SET key, the green light flashes three times, and the motor emits "beep" three times, indicating that the end position of backward has been stored
- 4. After calibrating and adjusting the throttle range, the motor can be operated normally.

#### 1. Startup phas

- In the normal state after startup, the red light is always on.
- The red light flashes continuously and rapidly: No throttle signal is detected by the ESC or the neutral position of the ESC does not match with the radio.
- The green light flashes N times: The number of Lipo Cells detection, flashes N times indicates there are N Lipo.

### 2. Driving stage

- The throttle trigger is in neutral range, and the green light goes out.
- When forwarding, the green light flashes; when the throttle is at the end position of forward, the green light is always on.
- When reversing, the green light flashes; when the throttle is at the end position of backward and the max. reverse force is set to 100%, the green light is always on
- 3. When relevant protection functions are triggered, the LED status means:
- The red light flashes continuously(single flashing, "京, 京, 京"); the ESC enters low-voltage protection status.
- Green light flashes continuously(single flashing, "\$\alpha, \$\alpha\$, \$\alpha\$"): the temperature of ESC is too high, and enters overheat protection status.

# 08 Troubleshooting

| Malfunction  | Cause   | Solution  |  |  |  |  |
|--|---|---|--|--|--|--|
| The indicator light is not on after power on, the motor cannot start.  | <ol> <li>The battery voltage IS not input to the ESC.</li> <li>The switch of ESC is damaged.</li> </ol>   | Check whether the power input channel has poor welding, and re-weld. Replace the switch.  |  |  |  |  |
| Power on and finish inspecting the number of Lipo cells<br>(Green light flashes N times), red light flashes quickly.   | <ol> <li>Throttle signal is not detected by the ESC.</li> <li>The neutral position of ESC and radio is unmatched.</li> </ol>  | 1. Check whether the throttle line is inserted reversely, whether the channel is inserted wrongly and whether the radio is on.<br>2. The throttle return to neutral position. Recalibrate throttle range.   |  |  |  |  |
| The radio increases throttle forward, the car reverses.  | The default rotation direction setting of motor and car<br>frame is unmatched.  | Set default rotation direction to another item via LED setting box.   |  |  |  |  |
| The motor suddenly stops rotating or the power output reduces obviously during rotation.   | 1. The receiver is interfered.<br>2. The ESC enters low voltage protection<br>3. The ESC enters overheat protection   | <ol> <li>Check why the receiver is interfered. Check battery level of transmitter.</li> <li>Red light flashes continuously is voltage protection, please replace battery.</li> <li>Green light flashes continuously is temperature protection. Please use it after the temperature drops.</li> </ol>  |  |  |  |  |
| When the throttle is in neutral position, the car slowly moves forward or backward.  | <ol> <li>The middle position of radio drifts and the signal is unstable.</li> <li>Throttle range is not calibrated well.</li> </ol>   | <ol> <li>Replace a radio with stable signal.</li> <li>Recalibrate throttle range or use throttle TRIM to calibrate midpoint.</li> </ol>   |  |  |  |  |
| When set throttle range, press Set key to set neutral<br>position, green light does not flash and emit "beep"<br>sound, or after setting neutral position, it cannot set<br>the end position of forward or backward. | <ol> <li>The throttle line of ESC is not inserted the correct channel<br/>of receiver.</li> <li>The throttle line of ESC is inserted reversely.</li> <li>The throttle channel setting does not match with the ESC.</li> </ol> | <ol> <li>Insert throttle line to The Throttle channel marked by receiver.</li> <li>Check receivers mark to ensure the throttle line of ESC is inserted into receiver correctly.</li> <li>If it is Futaba radio, set the throttle to "REV", try to keep the ratio before and after of the throttle channel at 5:5 for other radios.</li> </ol> |  |  |  |  |